

Questor Surveys Limited

FINAL REPORT and LOGISTICS

prepared for the

NATIONAL ENERGY BOARD of CANADA

PROJECT #06S02

**ACQUISITION OF HIGH RESOLUTION
AEROMAGNETIC DATA**

August 19 - September 24, 1995

in the

LIARD BASIN
N.W.T.

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Ron Sheldrake, Geophysicist
Questor Surveys Limited

January 1996

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1. INTRODUCTION

Questar Surveys Limited (Questar) a division of World Geoscience Corporation (WGC), undertook an airborne magnetic survey over portions of the Liard Basin, N.W.T. The survey was flown during the period August 19, 1995 through September 24, 1995. The aircraft used was mobilized from Questar's operational base located in Brantford, Ontario. This report summarizes the procedures used by Questar in acquiring, validating and processing the airborne geophysical data.

2. SURVEY AREAS

Area : Liard Basin
N.W.T.

Survey Co-ordinates :
NW Corner : 61 degrees N, 124 degrees W
NE Corner : 61 degrees N, 122 degrees W
SE Corner : 60 degrees N, 122 degrees W
SW Corner : 60 degrees N, 124 degrees W

3. SURVEY PARAMETERS

Aircraft Speed:	130kts / 240kph (nominal)
Mag Cycle Rate:	10Hz / 01 sec
Mean Sample Interval:	less than 15 metres
Mean Terrain Clearance:	150 metres
Mag Resolution:	0.001 nT
Total System Noise:	0.10 nT (Maximum)
Navigation Cycle Rate:	1Hz / 1.0sec
Radar Alt. Cycle Rate:	1Hz / 1.0sec
Barometric Alt. cycle rate:	1Hz / 1.0sec
Ground Mag. Cycle Rate	5 sec
Tracking Method:	Real-time differential GPS / Video camera

In-field Processing:	486 PC / printer
Flight Line Spacing:	400 metres
Tie Line Spacing:	1200 metres

4. EQUIPMENT SPECIFICATIONS

Aircraft:	Cessna C208.
Magnetometer:	Scintrex Cesium Vapor HB.
Data Acquisition:	Piondes PDAS 1000 (with realtime compensation).
Acquisition Software:	Piondes
3 Axis Fluxgate Mag.	Devco 9200 series.
Navigation Method:	NOVATEL 10-channel GPS Receiver / PNAV 2001.
Differential Nav. Method:	STARPIX Real-time Differential Transmission.
Radar Altimeter:	Sparri 100
Barometric Altimeter:	Rosemount Transducer.
Visual Tracking System:	Video camera, and video recorder.
Ground Mag (GSTN)	Geometrics G-856 Memory Magnetometer

5. SURVEY DETAILS

Survey Base:	Fort Nelson, British Columbia
Fuel Base(s):	Fort Liard, N.W.T
Ground Mag Location:	Airport, Fort Nelson
In-field Tests:	Heading Error / Parallax Error / Dynamic Compensation.

6. OPERATIONAL FIELD CREW

Crew Chief:	Jeani Monnaive
Pilots:	Jeanie Monnaive, Andre Roy, Bryan Patterson
Operators:	Philip Bell, Adam Barrett

Processor: Lori Moore
Technician: Bob Taylor

7. NAVIGATION

Aircraft navigation was provided using a Novatel GPS receiver unit. This unit was coupled to a STARFIX Real-time differential GPS system and the resulting, corrected positions data fed to both the PNAV 2001 navigation computer and to the PDAS 1000 data acquisition computer.

The PNAV 2001 is designed specifically for geophysical airborne surveys and has both a heads-up pilot display (left/right of track) and a moving map representation of where the aircraft is in relation to the survey area. The raw position and ephemeris data from the GPS satellite constellation together with the STARFIX corrected GPS positional information was recorded on a the PDAS 1000 in real time. The raw GPS satellite information was recorded onto DC2000 data tapes and then used in conjunction with the recorded GPS Base Station to provide a GPS post processed differentially corrected flight path using C3-NAV software. As a quality control measure the post-processed differentially corrected GPS positions are compared against the Real-time STARFIX positions.

The accuracy obtained was ± 5 meters or better, with a position fix recorded once per second.

8. TERRAIN CLEARANCE

The terrain clearance was a mean 150 metres above ground.

In conjunction with the Radar Altimeter, a Barometric Altimeter Transducer was also recorded.

9. DIURNAL VARIATION

The earth's natural magnetic field was monitored and recorded during the survey. The tolerance for diurnal activity was 10 nT over a linear cord in ten minutes.

10. MAGNETIC BASE STATION

A Geometrics G-856 memory magnetometer recorded diurnal activity during the day. This unit was located at F. Nelson airport. The magnetometer was set up in a known magnetically quiet location - free from cultural interference.

Type:	Geometrics G-856 memory magnetometer
Resolution:	0.1nT
Sample rate:	5 seconds
Noise Envelope:	0.5nT (Maximum)

The magnetometer records the Julian Day / Time in the local time zone, the reading number and the corresponding magnetic value. Time was synchronized daily to the aircraft acquisition system which is in turn synchronized to the GPS receiver which is in turn synchronized to the GPS satellites Atomic clock.

11. AIRCRAFT

The data acquisition platform used was, a Cessna 208, single engine, registration No. N9464F. This aircraft is owned and operated by Questor and complies to all Department of Transport regulations and is secured and insured accordingly.

12. AERBORNE MAGNETOMETER

The magnetometer sensor is located at the end of a tail stinger. The signal received by the magnetometer travels through a pre-amplifier located at the base of the tail stinger then through an interface board into the acquisition system (PDAS 1000).

Type:	Scintrex V-201 H-8 cesium vapour
Resolution:	0.001nT
Operating Range:	20,000 - 95,000nT

13. ALTIMETERS

The sensor height was recorded using both a Radar Altimeter and Barometric Altimeter. The radar altimeter has a circular analog indicator of the typical aircraft type which the pilot uses to maintain a constant ground clearance. The reading is also digitally recorded. This altimeter was calibrated by recording data at different heights over a flat surface and then determining the voltage output for a given height. This voltage is recorded and displayed to the operator on the acquisition display as a converted height to indicate feet AGL (above ground level).

The Barometric Altimeter (which is a simple pressure transducer) records the pressure altitude above sea level. It is also both recorded digitally and displayed for the operator.

14. VIDEO TRACKING

The aircraft uses a VHS type video recorder and camera. The camera is mounted inside the belly of the aircraft with a clear perspex window, enabling full ground view for the Auto Iris Lens.

The acquisition system (PDAS 1000) overlays the line number and fiducial values onto the video image. Each video tape was numbered sequentially and annotated with flight number before being filed and stored for future reference.

15. ACQUISITION SYSTEM

The Picodas PDAS 1000 data acquisition system computer is the heart of the airborne acquisition system. All data acquired in the aircraft is stored onto a hard disk contained within the PDAS 1000. This data is then transferred at the end of each flight or days production onto a DC2000 magnetic data cartridge, which in turn is transferred to the field office PC, then onward to the Sun Systems Sparc II.

The software used in this system has been developed in-house by Questor. Most of the hardware involved is commercially available, however some printed circuit boards, power supplies etc have been specifically designed and manufactured by Questor.

16. ACQUISITION FORMAT

Parameter	Units
Line number and heading:	String up to 9 characters
Flight Number:	Signed integer
Year:	Signed integer
Day:	Signed integer
Hour:	Unsigned byte 0 to 23
Minute:	Unsigned byte 0 to 59
Position (event in time):	Integer
Seconds:	Sec.
Fractional seconds:	.01s
Event:	.01s
X fluxgate Mag. axis:	mV
Y fluxgate Mag. axis:	mV
Z fluxgate Mag. axis:	mV
Barometric altimeter:	ft
Radar Altimeter:	ft
Raw magnetic's:	nT (nano Teslas)
Compensated magnetic's:	nT (nano Teslas)
GPS time:	sec.
Latitude/Longitude:	WGS-84 decimal degrees
Easting:	Meters
Northing:	Meters
GPS height: (height above spheroid)	Meters
GPS PDOP: (satellite quality)	Integer
GPS status:	Integer
GPS error:	Integer

17. RMS GRAPHIC CHART RECORDER

During data acquisition an analog record is produced by the RMS GR-33. A list of information is printed at the start of each recording session (first start-up) a complete list of parameters is printed as follows.

Questor Surveys Limited, header

Year, date and time

Acquisition system used, Mag. channel and number of Mag.

Manufacturer and program version number

Flight number

Job number

Client

Aircraft

Operator

Magnetometer type

Survey altitude

RMS chart speed

REM (any remarks relevant to that recording session input by the operator).

DOS path and ASCII file name (recording note pad).

RMS channel numbers and labels FSD (full scale deflection) and the units displayed.

Once the system has been initialized, the information printed at each line start is as follows:

Line number, i.e. 1001, attempt number, i.e. 1001 g, direction flown i.e. 1001.QN

Start fiducial (Fid.) number

Video number

Year Date, Time at start

Fid numbers are displayed at the top of the chart, while time is printed at the bottom.

Labels are printed for each trace starting from the top as follows:

FDD1	-	Fourth digital difference (displayed over 1°)
MAG1	-	Raw Mag. coarse scale (displayed over 5°)
MAG1	-	Raw Mag. fine scale (displayed over 5°)
DMAG	-	Trace indicating difference between the raw and compensated Mag. This trace shows how hard the dynamic compensation file is having to work to correct for aircraft maneuver and air turbulence (displayed over 5°)
CMA1	-	Compensated Mag. fine scale (displayed over 5°)
FGAT	-	Fluxgate magnetometer, total of all 3 axis, X, Y, and Z. Indicates aircraft maneuver and attitude.

RAD	Radar altimeter (displayed over 1").
BARO	Barometric altimeter (displayed over 1")

At the end of each line there is a comments prompt into which the operator can enter anything unusual that occurred during the line. The file name, line number, time at end and last Fid are printed, also the operator can select to print the last values recorded for each channel

18. SYSTEM CHECK AND CALIBRATIONS

18.1 Heading Check (static compensation)

To compensate the magnetometer data for the effect of the aircraft's magnetic field on the readings both static and dynamic compensation are used. This compensation was done prior to commencement of the first survey flight and then each time after that when it was considered that a possible change to the magnetic field of the aircraft had occurred.

Static Compensation

Winglets are mounted on either side of the magnetic sensor housing. A thin strip of a highly permeable amorphous glass metal, trade name Vitrovac, about 4 cm long and 0.25 cm wide has been taped to each winglet. The purpose of these metal strips is to equalize the magnetometer readings in the north/south directions to the readings obtained in the east/west directions.

The diurnal base station is recording during this time to allow for magnetic variations while recording these heading in the aircraft. This diurnal is then applied to the raw magnetic aircraft data to obtain a true indication of heading error. Any residual heading error can be determined by processing and removed by adding an accurate constant offset value.

18.2 Dynamic Compensation

The basis of this compensation is the reduction of motion induced noise on the measured magnetic field. This motion noise comes from the complex three dimensional magnetic signature of the airframe as it changes attitude with respect

to the earth's magnetic vector. The noise comes from permanent, induced and eddy current effects of the airframe plus additional heading effects of the Cesium vapor sensor itself.

The approach used by Questor has been developed by Picodas Group Inc. and consists of using four individual sets of coefficients, one for each heading flown on the survey.

A Devco three axis fluxgate magnetometer mounted in the aircraft stinger is used to measure the coupling of the three axes with the background magnetic field. This sensor is very sensitive to attitude changes and is used to accurately monitor the aircraft reference frame. The frequency response and sample. rate of the Picodas Analog Processor card used to measure the fluxgate signals is the same as that of the Picodas Magnetometer Processor card. This ensures that there is no phase distortion of these synchronized measurements. This leads to improved compensation throughout the passband of the system.

A series of Pitch, Roll and Yaw manoeuvre motions are carried out on each of the survey directions to vary this coupling and gather fluxgate and measured raw magnetic field data. This data is then processed using a ridge regression technique to find a stable set of coefficients for the model. When the compensation algorithm is run using the model and coefficients, either in real-time or post-processing, a magnetically compensated data set is generated.

The compensation manoeuvre "boxes" are flown at high altitude over magnetically quite areas. The pitch, roll and yaw manoeuvres are approximately 12° to 15° in amplitude of about 30 seconds duration each. A set of manoeuvres is carried out in each survey line direction as well as ~15° either side of each direction. A compensation "box" is flown each time re-compensation is required. The reduction of the data to calculate the coefficients was carried out on a 486 based personal computer using a program developed by Questor.

18.3 System Parallax

One of the processing parameters required to process the digital data is the parallax or offset in time, between the time the digital reading was taken by the instrument and the time the position fix for the fiducial of the reading was obtained. Each instrument - magnetometer, and altimeter may have a different parallax so the parallax must be computed for each instrument. A position fix may be obtained either by GPS position or by using the video to determine location. The parallax between the instrument and the GPS and the instrument and the video may be different.

To obtain this parameter two lines are flown in opposite directions over an anomaly. Stacked profiles of the lines are then done and the parallax adjusted till the anomaly position is the same for each line.

The parallax correction derived is the correction to be applied to each survey line. A positive parallax indicates the instrument reading is ahead of the position for the fiducial. Each integer fiducial occurs every second so the parallax can be expressed in either fiducials or seconds.

The correct fiducial is computed by

$$Fc = Fr - Ip$$

where

Fc = Parallax corrected fiducial

Fr = Fiducial for recorded reading

Ip = Instrument parallax

For this project, as the GPS was the prime position source and the video was not used at all for positioning, no parallax was worked out between instrument and video.

Previous experience with video positioning would suggest that the parallax derived using the GPS will be a good approximation.

The parallax to be applied when using the analogue charts will be the same as that used for the digital data. If an anomaly is identified on the chart and a fiducial number recorded then the corrected fiducial will be as per the above formula.

19. MONITORING FLIGHT PATH

GPS flight path was recovered and plotted daily to ensure it was within specifications. Any data not within specification was re-flown at the earliest possible opportunity. This data used was the differentially corrected flight path, and the system is set up such that it shows the number of satellites used, the quality of positioning and the amount of definite position fix's.

20. FLIGHT SUMMARY

Start of production:	August 19, 1995
End of production:	September 24, 1995

21. FLIGHT CONDITIONS

Over the survey period a variety of climatic and atmospheric conditions were experienced. Cloud cover in the mountains and turbulence were experienced at times, some days of excessive winds, caused adverse flying conditions.

22. DOWNTIME

A moderate amount of downtime was encountered during the operation due to severe weather conditions or diurnal activity. Downtime due to aircraft or equipment problems was minimal, amounting to just a few days over the course of the survey.

23. DAILY OPERATIONS REPORT

A daily operations report was compiled by the crew chief for the duration of the survey. The report documents the date, flight number, flight times, kilometres flown and accepted, and reasons for any downtime, and a comments column stating weather condition, equipment condition.

24. PROCESSING EQUIPMENT USED IN FIELD

For the duration of the survey, a field office was established by Questor at Fort Nelson. The equipment listed below was transported and set up on location.

- 1 x 486 IBM compatible computer
- 1 x Epson dot matrix printer
- 1 x Telebit modem

25. VALIDATION AND VERIFICATION PROCEDURES

Each evening or after the day's production the data was transferred onto the field office computer system for verification of the day's flying. This consisted of the following.

1. Checking the statistics for each line.
2. Plotting the day's diurnal to ensure the variation was within specifications.
3. Plotting profiles of any lines that could have potential problems.
4. Noise plots were created and profiled for each line.
5. Calibration test line data were plotted to ensure equipment was operating within tolerances.

26. DATA PROCESSING PROCEDURE

Magnetic Diurnal Data

All magnetic diurnal data was obtained from the Geometric magnetometer base station set up at the airstrip in Fort Nelson. Data from the magnetometer was recorded every 5 seconds. The data was downloaded from the magnetometer to a 486 based personal computer. It was transferred by modem to the Sun processing computer, at the data processing centre in Calgary. The data were checked and corrected for spikes. Single reading spikes were either manually or automatically edited and replaced with an interpolated result. The diurnal data were also checked to see that the change in diurnal readings during the course of the survey flight did not exceed survey specifications. When this occurred the affected survey lines or line segments were reflown.

Radar Altimeter Data

The height of the aircraft above the ground was recorded every 0.1 second using a radar altimeter. A fourth difference program was used to identify spikes prior to either manual or automatic correction. The altimeter data was used as a validation control of each crossover during tie line levelling of the magnetic data and to correct the radiometric data for atmospheric attenuation effects above or below the nominated survey height.

Barometric Altimeter Data

The height of the aircraft above sea level was recorded every 0.1 second using a barometric altimeter. A fourth difference program was used to identify spikes prior to either manual or automatic correction. The barometric altimeter data was not used in the basic processing.

Flight Path Location

The aircraft's position was determined using a Novatel GPS navigation system. GPS positions were recorded every second. A colour VHS video camera was used for verification but was not used in any stage of the processing. The GPS data was recorded in the WGS84 geodetic datum. During the first processing stage the GPS data were transformed into eastings and northings of the local geodetic datum. A speed check was then run on the data. The resulting velocities were checked and any data causing abnormal speeds were deleted and reflow.

Magnetic Data Processing

Real-time compensated and uncompensated magnetic data, were recorded digitally every 0.1 of a second. Both channels were transferred from the aircraft to the processing computer system where the fourth difference program for the identification of possible spikes. Single reading spikes were either manually or automatically edited. Multiple reading spikes were flagged as invalid and if necessary that section of the line was reflow. The same digital compensation co-efficients as used in the aircraft were then applied to the edited uncompensated magnetic data to produce a post flight compensated magnetic data channel.

The following correction and levelling procedures were then applied to the raw edited compensated data to produce preliminary levelled magnetic data.

a) Diurnal

The synchronized digital diurnal data was first subtracted from a base level of 58,780 nT. The resultant values were then added to the airborne magnetic readings by synchronizing the time from the start and end of each line, to produce a diurnally corrected reading.

b) Parallax

A parallax correction of 0.3 seconds was then applied to the diurnally corrected data.

c) International Geomagnetic Reference Field (IGRF)

The International geomagnetic reference field was calculated at every recovery point.

d) Tie Line Levelling

A crossover program was then used to compute the magnetic difference between each tie line and the traverse line intersection. These differences were applied to the traverse line data to level the traverse lines to the tie lines. A crossover difference was automatically rejected if the total gradient ($G = \text{sqrt}(G_{\text{tie}}^2 + G_{\text{trv}}^2)$) of the tie line and traverse line at the crossover exceeded 0.15 nT/fid.

e) Preliminary Gridding and Inspection

The data was then gridded and from the computed grid image enhancements were displayed on the processing computer screen. These were inspected for inconsistencies and for errors which were investigated by the on-site data processor and geophysicist. Appropriate corrections and / or adjustments were made if required.

f) Micro Levelling

After corrections had been applied to the data, a correction was applied to remove some remaining sub-nano tesla distortions evident only after applying image enhancing algorithms to the gridded data. These distortions are usually the residual noise of the crossover corrections.

g) Gridding

The corrected and levelled magnetic data was gridded to interpolate along lines to obtain grid column intersection values. These were then sorted into columns and a polynomial interpolation was used to determine row values along each column.

Gridding parameters were as follows:

Grid cell size - 130 metres

27 SUMMARY

A High Resolution Survey of 44,000 km was flown over the Fort Liard Mapsheet 95B. The aeromagnetic survey results indicate broad regional basement features as well as structures within the sedimentary section. Fault traces can be seen in the data, which may provide useful information in hydrocarbon exploration programs.

Report submitted.

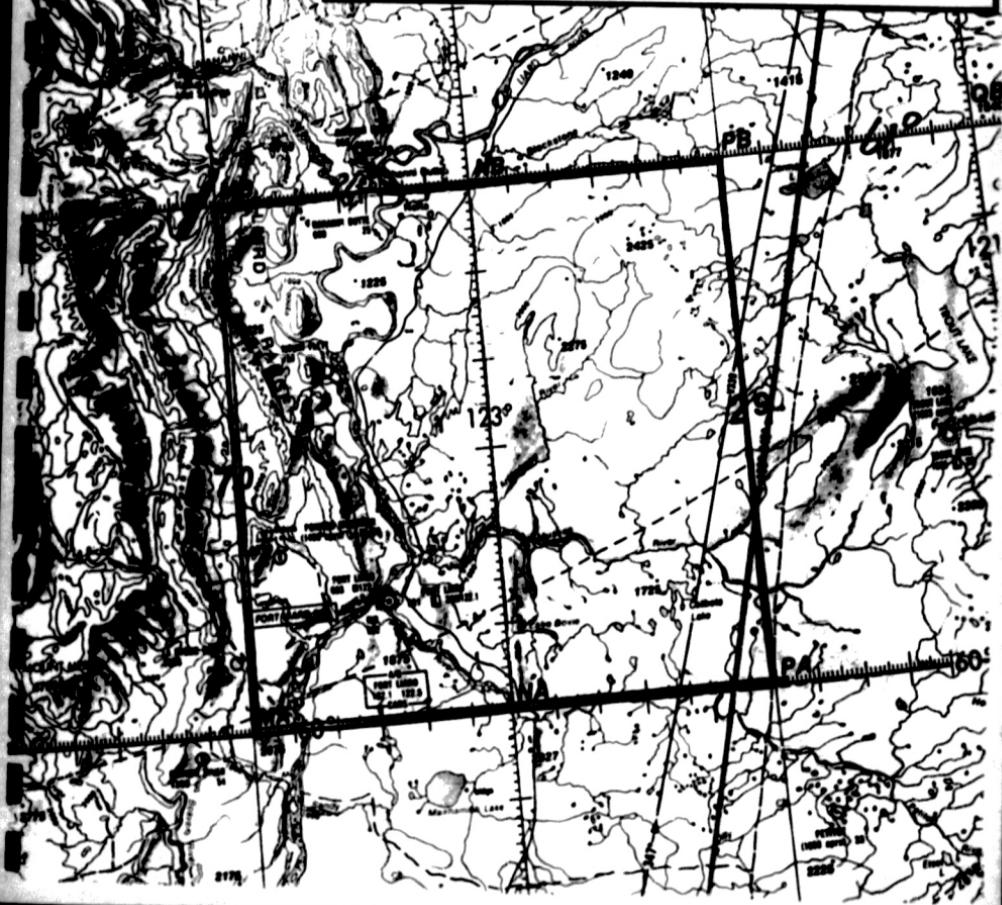
Geophysical

APPENDIX A

SURVEY AREA MAP

QUESTOR SURVEYS LIMITED

FORT LIARD BASIN - AREA MAP
for a
**HIGH RESOLUTION AEROMAGNETIC
SURVEY**
FLOWN : AUGUST 19 - SEPTEMBER 24, 1995



APPENDIX B

FLIGHT LINE MAP

APPENDIX C

TOTAL MAGNETIC INTENSITY CONTOUR MAP

APPENDIX D

TOTAL MAGNETIC INTENSITY
Stacked Second Vertical Derivative

APPENDIX B

DAILY REPORTS

QUESTOR SURVEYS LIMITED
 Port Nelson Head
 P.O. Box 248, Port Nelson B.C. Canada
 Phone: (604)774 6811 Fax: (604)774 6711

**DAILY OPERATIONS
 REPORT**

Job #Q8502
 N9464F

WEEK ENDING
 Aug. 20 1993

DATE	BASE	FLT	AREA	FLIGHT TIMES			KILOMETRAGE		UNSERVICABILITY *				COMMENTS
				FRST	TEST	PROD	TOTAL	FLOWN	ACCEP	A/C	EQUIP	DISUR	
MON	Job												
Aug. 14	B.C. Canada												
TUE	Job												
Aug. 15	Port Nelson												
	B.C. Canada												
WED	Job Q8502	1	2.0			2.0							
Aug. 16	Port Nelson	1											
	B.C. Canada												
THU	Job Q8502	1											
Aug. 17	Port Nelson	1											
	B.C. Canada												
FRI	Job Q8502	1											
Aug. 18	Port Nelson	1											
	B.C. Canada												
SAT	Job Q8502	1	1	1.4	0.4	2.4	4.2	1227	1227				
Aug. 19	Port Nelson	1	1	1.4		2.7	4.1						
	B.C. Canada												
SUN	Job Q8502	2	1	1.4		3.6	5.0	1333	1333	25	25		
Aug. 20	Port Nelson	2	1	1.4		2.6	4.0						
	B.C. Canada												
TOTAL FOR WEEK								2,560	2,560	COMMENTS:			
TOTAL FOR JOB Q8502								2,560	2,560				

* Reported as a percentage of survey day. * Tests & reflights in the same column

PILOT: J. Monasive
 PILOT: Andre Roy

OPERATOR: Adam Barrett
 OPERATOR: Phil Bell

PROCESSOR: A.B / P.B / J.M.
 CREW CHIEF: Jaime Monasive

QUESTOR SURVEYS LIMITED

Port Nelson Hotel
 P.O. Box 240, Port Nelson B.C. Canada
 Phone: (604)774 6811 Fax: (604)774 6711

DAILY OPERATIONS
REPORT

Job #Q8502
 N9464F

WEEK ENDING
 Aug. 27, 1995

DATE	BASE	FLT	AREA	FLIGHT TIMES			KILOMETRAGE		UNREACHABILITY*			WX	COMMENTS	
				FRVR	TEST	PROD	TOTAL	FLOWN	ACCEP	AC	SOUP	DEUR		
MON	Job Q8502	3	1	1.4		3.2	4.6	1551	1551					3 lines of production in area 1 in am.
Aug.	Port Nelson	3	1	1.4		3.1	4.5							3 tie lines and 1 traverse in afternoon flight.
21	B.C. Canada													Using Peace River Base GPS data.
TUE	Job Q8502	4	1	1.2			1.2	1488	1488					Mountains covered in cloud waited for wx.
Aug.	Port Nelson	4		0.4		3.2	3.6							Flew 9 traverse lines and 3 tie lines
22	B.C. Canada		1	1.2		3.0	4.2							Still using Peace River Base GPS data
WED	Job Q8502									100				Aircraft in for Phase inspection.
Aug.	Port Nelson													
23	B.C. Canada													
THU	Job Q8502	5	1	1.2		3.8	5.0	1886	1886				25	Attempted tie lines in mountains. WX poor.
Aug.	Port Nelson	5	1	1.2		3.4	4.6							Flew 8 tie lines in am and 8 tie lines in pm.
24	B.C. Canada													Still using Peace River GPS data.
FRI	Job Q8502	6	1	1.2		3.9	5.1	1790	1790				25	Early morning wx and Baro Alt. problem.
Aug.	Port Nelson	6	1	1.2		3.5	4.7							Production flight. 8 tie lines am & 5 in pm.
25	B.C. Canada													Base GPS now operational
SAT	Job Q8502	7	1	1.2		4.1	5.3	1957	1957				25	Fog and low clouds in the mountains.
Aug.	Port Nelson	7	1	1.2		4.1	5.3							Flew 7 tie lines and 2 traverse lines in am.
26	B.C. Canada													Flew 7 tie lines and 18 traverse lines in pm.
SUN	Job Q8502	8	1	1.4		4.0	5.4	1376	1376					
Aug.	Port Nelson	8	1	0.2			0.2							Production flights in am & pm.
27	B.C. Canada			1.8		2.6	4.4							L. Moore departed, P. Bell arrived
	TOTAL FOR WEEK				16.2	6	41.9	58.1	9,968	9,968				Kilometres remaining: 38,036
	TOTAL FOR JOB Q8502				23.8	6.4	53.2	77.4	12,528	12,528				

* Reported as a percentage of survey day. * Tests & reflights in the same column

PILOT: J. Monseive

PILOT: B. Patterson

OPERATOR: Adam Barrett

OPERATOR: L. Moore

PROCESSOR: A.B./L.M./J.M.

CREW CHIEF: Jaime Monseive

QUESTOR SURVEYS LIMITED
 Fort Nelson Hotel
 P.O. Box 240, Fort Nelson B.C. Canada
 Phone: (604)774 6811 Fax: (604)774 6711

**DAILY OPERATIONS
 REPORT**

Job #Q8502
 N9464F

WEEK ENDING
 Sept 3, 1995

DATE	BASE	FLT	AREA	FLIGHT TIMES			KILOMETRAGE		UNSERVICABILITY *				COMMENTS
				PIRBY	TEST	PROB	TOTAL	FLOWN	ACCEP	A/C	SOUP	DRIB	
MON Aug 28	Job Q8502	9	1	1.2			3.9	5.1	1710	1710			25
	Fort Nelson												8 Traverse lines in am. Weather poor in mountains. 6 traverse lines in pm.
	B.C. Canada												B. Patterson departed today.
TUE Aug 29	Job Q8502	10	1	1.4			3.9	5.3	1653	1653			Mountains covered in cloud.
	Fort Nelson	10	1	1.4			3.4	4.8					Flew traverse lines in am and pm.
	B.C. Canada												K. Harrington in town
WED Aug 30	Job Q8502	11	1	1.3			4.0	5.3	1720	1720			25
	Fort Nelson	11	1	1.3			3.7	5.0					Fl. attempt in mountains. Excessive winds.
	B.C. Canada												Continued with traverse lines.
THU Aug 31	Job Q8502	12	1	1.3			3.5	4.8	1785	1785	25	25	Fl. attempts in mountains. Top turbulent.
	Fort Nelson	12	1	1.2			3.4	4.6					Continued with traverse lines.
	B.C. Canada												836 Base Mag. Inoperable. Using Peace River
FRI Sept 1	Job Q8502	13	1	1.3			-	1.3			25	25	Fl. attempt. Returned from area due to fog.
	Fort Nelson	13	1	0.4			2.2	2.6	1170	1167			Flew out to continue with traverse lines.
	B.C. Canada	13	1	1.3			3.1	4.3					Using mag base station from Peace River.
SAT Sept 2	Job Q8502	14	1	1.3	0.5		3.0	4.8	1686	1686	25	25	Very strong winds in survey area.
	Fort Nelson	14	1	1.3			4.2	5.5					Comp box in am. Continued with trv. lines.
	B.C. Canada												Using mag base station from Peace River
SUN Sept 3	Job Q8502	15	1	0.8			0.8	0.8			25	25	Landed at Pt. Liard to wait out weather.
	Fort Nelson	15	1	0.4			4.1	4.5	1082	1082			Continued with traverse lines.
	B.C. Canada	15	1	1.0			4.1	4.1					Using mag base station from Peace River.
TOTAL FOR WEEK				18.6	0.5	49.9	48.4	11,614	11,614	COMMENTS:			
TOTAL FOR JOB Q8502				41.8	0.9	103.1	145.8	24,142	24,142	836 metres remaining: 18,422			

* Reported as a percentage of survey day. * Tests & reflights in the same column

PILOT : J. Monsaive
 PILOT : Andre Roy

OPERATOR: Adam Barrett
 OPERATOR: Phil Bell

PROCESSOR: A.B / P.B / J.M
 CREW CHIEF: Jaime Monsaive

QUESTOR SURVEYS LIMITED

Fort Nelson Hotel
 P.O. Box 240, Fort Nelson B.C. Canada
 Phone: (604)774 6811 Fax: (604)774 6711

**DAILY OPERATIONS
REPORT**

Job #Q8502
 N9464F

WEEK ENDING
 Sept 10, 1995

DATE	BASE	FLT	AREA	FLIGHT TIMES			KILOMETRAGE		UNIQUEX CAPABILITY				COMMENTS
				PRVY	TEST	PROD	TOTAL	FLOWN	ACCEP	A/C	EQUIP	SHUR	
MON	Job Q8502												
Sept 4	Fort Nelson												
	B.C. Canada												
TUE	Job Q8502	16	1	1.4		3.0	5.2	1247	1247				
Sept 5	Fort Nelson	16	1	1.1		0.7	1.8						
	B.C. Canada												
WED	Job Q8502	17	1	1.3		3.5	4.8	1148	1148				
Sept 6	Fort Nelson	17	1	0.8		1.4	2.2						
	B.C. Canada												
THU	Job Q8502	18	1	1.3		4.1	5.4	1575	1575				
Sept 7	Fort Nelson	18	1	1.1		2.4	3.5						
	B.C. Canada												
FRI	Job Q8502	19	1	1.0		3.8	4.9	883	883				
Sept 8	Fort Nelson												
	B.C. Canada												
SAT	Job Q8502	20	1	1.3		3.0	4.3	1293	1293				
Sept 9	Fort Nelson	20	1	1.3		2.4	3.7						
	B.C. Canada												
SUN	Job Q8502	21	1	1.4		4.0	5.4	1862	1862				
Sept 10	Fort Nelson	21	1	1.4		4.0	5.4						
	B.C. Canada												
TOTAL FOR WEEK				14.2	0	32.4	46.6	7,928	7,928	COMMENTS:			
TOTAL FOR JOB Q8502				36.0	0.9	135.5	192.4	32,070	32,070	Kilometres remaining: 16,494			

* Reported as a percentage of survey day. * Tests & reflights in the same column

PILOT : J. Monsalve
 PILOT : Andre Roy

OPERATOR: Adam Barrett
 OPERATOR: Phil Bell

PROCESSOR: A.B / P.B / J.M.
 CREW CHIEF: Jaime Monsalve

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**DAILY OPERATIONS
 REPORT**

Job #Q8502
 N9464F

WEEK ENDING
 Sept 17, 1995

DATE	BASE	FLT	FLIGHT TIMES			KILOMETRAGE		UNSERVICEABILITY				COMMENTS
			AREA	FERRY	TEST	PROD	TOTAL	FLOWN	ACCEP	A/C	EQUIP	
MON Sept 11	Job Q8502 Port Nelson B.C. Canada	22	1	1.4		4.1	5.5	961	961			75
TUE Sept 12	Job Q8502 Port Nelson B.C. Canada	23	1	1.4		3.9	5.3	920	920			50 50
WED Sept 13	Job Q8502 Port Nelson B.C. Canada	24	1	1.4		3.8	5.2	1816	1816			25 25
THU Sept 14	Job Q8502 Port Nelson B.C. Canada		1	1.1			1.1					50 25 25
FRI Sept 15	Job Q8502 Port Nelson B.C. Canada	25	1	1.8		3.6	5.4	899	899			50 25 25
SAT Sept 16	Job Q8502 Port Nelson B.C. Canada	26	1	1.4		2.3	3.7	385	385			50
SUN Sept 17	Job Q8502 Port Nelson B.C. Canada	27	1	1.4		3.9	5.3	357	357			50
TOTAL FOR WEEK			12.7	0	20.5	41.2	6,535	6,535				Comments:
TOTAL FOR JOB Q8502			69.0	0.9	166.7	236.6	38,695	38,695				Kilometres remaining: 3,959

* Reported as a percentage of survey day. * Tests & reflights in the same column

PILOT: J. Monsalve
 PILOT: Andre Roy

OPERATOR: Adam Barrett
 OPERATOR: Phil Bell

PROCESSOR: A.B/P.B/J.M.
 CREW CHIEF: J. Monsalve

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**DAILY OPERATIONS
REPORT**

Job #Q8502
N9464F

WEEK ENDING
Sat 24 1995

DATE	BASE	FLT	AREA	FLIGHT TIMES			KILOMETRAGE			UNSERVABILITY*			COMMENTS			
				FERRY	TEST	PROD	TOTAL	FLOWN	ACCEP	A/C	EQUIP	DIUR				
MON Sept 18	Fort Nelson B.C. Canada	Job Q8502	1	1.3		3.3	4.6	931.2	931.2				Production flight in am/pm			
				1.4		2.9	4.3						Good weather, no problems			
													Jamie Monsees departs for Houston			
TUE Sept 19	Fort Nelson B.C. Canada	Job Q8502	1	1.4		3.9	5.3	1694.9	1694.9				Production flight in am/pm			
				1.4		3.6	5.0						Good weather no problems			
													Andre Roy leaves for Calgary			
WED Sept 20	Fort Nelson B.C. Canada	Job Q8502	1				0	0	0	100%			Aircraft in shop for 100 hour			
													No Production			
THU Sept 21	Fort Nelson B.C. Canada	Job Q8502	1							50%	15%	35%	Aircraft is completed			
				2.1		1.9	4.0	373.1	373.1				PM flight-Turbulence bad in hills			
													some problems with PNAV			
FRI Sept 22	Fort Nelson B.C. Canada	Job Q8502	1	1.3		3.2	4.5				15%		Weather was great finished area			
				1.3		1.3	2.5	850	850				Problems with RMS and PNAV			
													All reflights completed			
SAT Sept 23	Fort Nelson B.C. Canada	Job Q8502	1				0	0	100%				No flying, waiting for any re-flights			
													preparing to move to Peace River			
SUN Sept 24	Fort Nelson B.C. Canada	Job Q8502	2.0	0.5	2.5		110	110	100%				Finished assigned re-flights			
				0	0	2.2	0	0					Ferry aircraft to Peace River			
													Crew moves to Peace River			
TOTAL FOR WEEK				9.4	0	20.6	34.9	3,959.2	3,959.2				COMMENTS: Kilometres remaining: 0			
TOTAL FOR JOB				115.6	63.3	224.6	348.4	42,564.2	42,564.2							

* Reported as a percentage of survey day. * Tests & reflights in the same column

PILOT : Bryan Patterson
PILOT : Andre Roy

OPERATOR: Adam Barrett
OPERATOR: Phil Bell

PROCESSOR: Adam Barrett
CREW CHIEF: Bryan Patterson

APPENDIX F

TOTAL MAGNETIC INTENSITY IMAGE